

21. A system, comprising:  
a damper operable to provide a damping force in response to a  
reception of a first operating current; and  
5 a controller,  
wherein said controller is operable to generate a second operating  
current as a function of a desired force level of the damping force,  
wherein said controller is operable to determine a scale factor and an  
offset value as a function of an operating temperature of the damper and a velocity  
10 of the damper, and  
wherein said controller is operable to provide the first operating  
current to the damper in response to a determination of the scale factor and the  
offset value.
- 15 22. The system of claim 21, wherein  
said controller is further operable to generate a third operating  
current as a product of the second operating current and the scale factor, and  
said controller is further operable to generate the first operating  
current as a summation of the third operating current and the offset value.  
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23. The system of claim 21, wherein  
said controller is further operable to generate a third operating  
current as a summation of the second operating current and offset value, and  
said controller is further operable to generate the first operating  
25 current as a product of the third operating current and the scale factor.